

# **CANopen Series Products**

## **PWM module of CANopen Slave**





99 107.0 107.0 Unit: mm

**Dimensions** 

PWM (Pulse width modulation) is a powerful technique for controlling analog circuits. By using digital outputs, it can generate a waveform with variant duty cycle and frequency to control analog circuits. CAN-2088C, a CAN bus remote I/O modules with CANopen protocol, provides 8 PWM output channels and 8 digital inputs channels with high-speed counter function. It can be used to develop practical and economical analog control systems in the CANopen network.

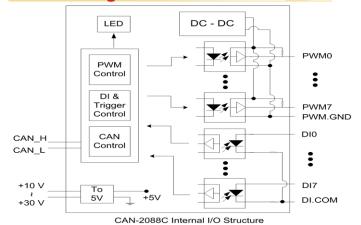
### Features

- Hardware-controlled PWM output.
- PWM output frequency:  $0.2 \text{ Hz} \sim 500 \text{ kHz}$  with  $0.1\% \sim 99.9\%$  duty cycle.

CAN-2088C

- PWM Output Modes: software trigger / hardware trigger.
- Trigger each PWM output individually or all PWM outputs synchronously.
- Support Burst output mode and Continue output mode.
- Provide 32-bit 500 kHz high-speed counter for each DI channel.
- Pass the validation of CANopen conformance test.
- Provide EDS file for CANopen master interface.

## Block Diagram



#### **I/O Pin & Wire Connection**

Terminal No.	Pin Assignment	Output Type	ON State LED ON Readback as 1	OFF State LED OFF Readback as 0
[ 01	PO.0		Relay On	Relay Off
[ □ 02	P0.1	Drive Relay		
[ 03	PO.2		□ POX	□□ x □⊖ PO X
ু ৹ ( 04	PO.3			
∫ 05	PO.4	Resistance Load		
[ □ 06	PO.5		†di melleov	tax relleav
07	PO.6	Loau	PO X PO.GND	PO X
08	P0.7		V ———	v
[ 09	PO.GND	Input Type	ON State LED ON Readback as 1	OFF State LED OFF Readback as 0
[ 0 10	PO.GND	Relay Contact	Relay On	Relay Off
[ 11	DI.0		+ <u>+</u> D) X	+ <u></u> DI X
[ · 12	DI.1		Relay Close DI.GND	Relay Open DI.GND
្រី ា 13	DI.2	TTL/CMOS	Voltage > 10 V	Voltage < 4 V
<u></u> 14	DI.3	Logic	Logic Power  C  Logic Level Low  DI X  DI.GND	Logic Power O Logic Level Low DI X DI.GND
[ o 15	DI.4			
[ □ 16	DI.5	NPN Output	Open Collector On	Open Collector Off
[ 17	DI.6		DI X DI.GND	OFFE □ □ DI X □ □ DI.GND
18	DI.7	PNP Output	Open Collector On	Open Collector Off
[ 19	DI.GND		DIX	DIX
20	DI.GND	- Carpar	ON-5 □ DI.GND	OFF- DI.GND

## CAN Pin & Baud Rate Rotary

CAN V+	1_5	Pin 5
CAN_V+		Pin 5
CAN_L		Pin 4
CAN_Shield		Pin 3
CAN_L		Pin 2
CAN_GND	$ \bullet\rangle$	Pin 1

Switch Value	Baud Rate
0	10 kbps
1	20 kbps
2	50 kbps
3	125 kbps
4	250 kbps
5	500 kbps
6	800 kbps
7	1000 kbps
	0 1 2 3 4 5

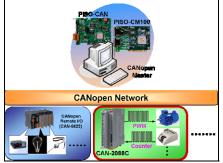


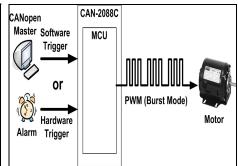


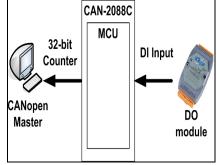
# Hardware Specifications

CAN Interface					
Connector	5-pin screwed terminal block (CAN_GND, CAN_L, CAN_SHLD, CAN_H, CAN_V+)				
Baud Rate (bps)	10 k, 20 k, 50 k, 125 k, 250 k, 500 k, 800 k, 1 M				
Terminator Resistor	Switch for 120 Ω terminator resistor				
Node ID	1~99 selected by rotary switch				
Protocol	CANopen DS-301 ver4.02, DS-401 ver2.1				
No. of PDOs	10 Rx, 10 Tx (support dynamic PDO)				
PDO Mode	Event Triggered, Remotely requested, Cyclic and acyclic SYNC				
Error Control	Node Guarding protocol and Heartbeat Producer protocol				
Emergency Message	Yes				
PWM Interface					
Channels	8 (Source)				
Frequency Range	0.2 Hz ~ 500 kHz (non-continuous, the min. unit of the high/low level signal is 1 us).				
PWM Mode	Continue mode, Burst mode, Hardware trigger mode, Software trigger mode				
ESD Protection	ESD Protection 4 kV Contact for each channel				
DI Interface					
Channels	8 (Sink)				
Counter Frequency	32-bit, 500 kHz Max.				
ESD Protection	4 kV Contact for each channel				
LED					
Round LED	PWR LED, RUN LED, ERR LED				
I/O LED	8 LEDs as PWM, 8 LEDs as Digital Input, and 1 LED as terminal resister indicator				
Power					
Input range	Unregulated $+10 \sim +30 \text{ V}_{DC}$				
Power Consumption	3.5 W				
Mechanism					
Installation	DIN-Rail				
Dimensions	32.3 mm x 99 mm x 77.5 mm (W x L x H)				
Environment					
Operating Temp.	-25 ~ 75 ℃				
Storage Temp.	-40 ~ 80 ℃				
Humidity	5 ~ 95% RH, non-condensing				

## Applications







# Ordering Information

CAN-2088C CANopen Module of 8-channel PWM and 8-channel DI with High-speed Counters.